

UDM_{LC}



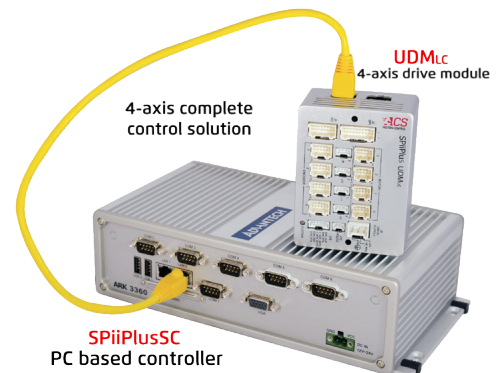
EtherCAT[®] Dual/Quad Axis Drive Module

- > Universal dual/quad axis Drive Modules for EtherCAT networks
- > 12Vdc to 48Vdc, up to 5A continuous and 10A peak current
- > Digital control for easy setup and diagnostics
- > Universal drive, supporting any of the following type of motors by software settings only: 2, 3 phase AC Servo / DC brushless with sinusoidal commutation, DC brush, voice coils, closed and open loop step motors
- > Feedback
 - > 4 digital incremental encoders
 - > 2 absolute encoders (optional)
- > Digital I/O (all can be used as general purpose I/O):
 - Inputs: 4 Registration Mark
 - Outputs: 1 PEG, 4 motor brake (24V, 0.5A)
- > SPI interface for special feedback devices
- > Compact footprint: 100x75x48 mm³

The UDM_{LC} is a series of small footprint EtherCAT modules with dual/quad-axis universal drives for servo, stepper, and voice coil motors with a power range of 10W to 200W. The type of motor is selected by the user and can be set differently for each drive.

This product addresses the needs of demanding multi-axis motion applications with limited space, such as moving inspection heads, small manipulators, and table-top motion stages. The miniature size, low weight, and minimal cable interface makes the UDM_{LC} ideal for mounting remotely on moving axes. It is available in three current levels (cont./peak per axis): 1.25/2.5A, 2.5/5A or 5/10A (dual axis version only), and has inputs for four digital incremental and two absolute encoders.

The unit is powered by a 12 to 48Vdc drive supply voltage and by a separate 15 to 48Vdc control supply that keeps all logic signals alive during emergency conditions. The UDM_{LC} is panel or din rail mountable.



Specifications

Product (x – number of axes) (yyy – additional options)	UDMlc x001yyy	UDMlc x002yyy	UDMlc x005yyy
Number of axes	2,4	2,4	2
Motor voltage input range [VDC]	12-48		
Control voltage input [VDC]	15-48		
Phase current (Cont./ Peak) Sine amplitude [A]	1.25/2.5	2.5/5	5/10
Phase current (Cont./ Peak) RMS [A]	0.9/1.8	18/3.6	3.6/7.2
Peak current time [sec]	1		
Max. output voltage to motor [VDC]	(Drive supply) x 93%		
Max. RMS input current at 80Vdc [W]	4.3	8.6	8.6
Min. load Inductance, at maximum motor voltage [mH]	0.050		
Max. Heat dissipation per axis [W]	0.7	2	6
Weight [gram]	250		
Dimensions [mm ³]	100x75x48		
Standards	CE, UL		

Servo

A standard comprehensive set of powerful algorithms to enhance accuracy, move & settle time, smooth velocity, stability and robustness

- > Advanced PIV cascaded structure
- > Loop shaping filters
- > Gain Scheduling
- > Gantry MIMO control (2.5/5model only)
- > Dual feedback / loop control
- > Disturbance rejection control

Optional **ServoBoost™** algorithm that provides better, more consistent servo performance, insensitive to noise and large changes in the system

Drives

Type: digital current control with field oriented control and space vector modulation
Current ripple frequency: 40 kHz. Current loop sampling rate: 20 kHz
Programmable Current loop bandwidth: up to 5 kHz
Commutation type: sinusoidal. Initiation with and without hall sensors
Switching method: advanced unipolar PWM
Protection: over voltage, motor phase-to-phase short circuit, motor phase to ground short circuit, over-current, over-temperature

Supplies

The module is fed by two power sources. A motor supply and control supply. During emergency conditions there is no need to remove the control supply
Drive Supply
Range: 12Vdc to 48Vdc
Current rating should be calculated based on actual load
Control Supply
Range: 15Vdc to 48Vdc
Maximum input power: 15W
Input current: < 1A

Motor Types

Two- and three-phase permanent magnet synchronous (DC brushless/AC servo), DC brush, voice coil, Two- and three-phase stepper (micro-stepping open or closed loop), five-phase stepper*.
* Consult ACS.

Accessories

UDMlc-ACC1 – A set of mating connectors
UDMlc-ACC2 – A set of 50cm cables with assembled mating connectors
UDMlc-ACC3 – Din-rail mounting kit

Certifications

CE: Yes
Electrical Safety: IEC 61010-1
EMC: EN 61326-1
UL: UL508C

Feedback

Types: incremental digital encoders, optional: absolute encoders
Incremental Digital Encoder: Four, one per axis. A&B,I and Clk/Dir.
Type: Differential RS-422 or single-ended
Max. rate: RS-422 - 50M quad counts/sec, Single-ended: 2M quad counts/sec.
Protection: Encoder error, not connected
Absolute encoders (optional): Total of two. EnDat 2.1(Digital)/2.2, Panasonic, SmartABS, BiSS-A/B/C and SSI
Hall inputs: Four, a set of three per axis. Type: single-ended, 5V, source, opto-isolated
Input current: <7mA
5V feedback supply: Feedback devices are fed by a 5V±5% supply.
Total available current to all encoders is 1A

Digital I/O

Safety Inputs: Left and right limit inputs per axis
Type: Single-ended, 24V±20%,opto isolated, source E-Stop: 24V, Max., opto isolated, two terminal, input current 4-14mA. Unused safety inputs can be used as general purpose inputs
Registration MARK: Four. Fast, 24V±5%, opto-isolated, two terminals. Can be configured as 'sink' or 'source'. 4-10mA max. input current.
Can be used as general purpose fast inputs
Motor Brake Outputs: Four, opto-isolated, 24V±20%, 0.5A per output. Can be used as general purpose outputs
Position Event Generator (PEG): One, RS422. Can be used as general purpose output. Pulse width 26nSec to 1.75mSec
Maximum rate with RS422 outputs: 10MHz
SPI Interface Two. requires customized software to activate**.
**Consult ACS.

Environment

Operating range: 0 to +50°C
Storage and transportation range: -25 to +70°C
Humidity (operating range): 5% to 90% non-condensing

Communication

Two EtherCAT ports, In and Out

Ordering Options

Ordering Options	Field	Example User Selection	Values
Number of axes	1	4	2, 4
Continuous Current (Peak is double)	2	002	001-1.25A, 002-2.5A, 005-5A (5A only dual axis version)
Total number of feedback channels	3	4	2, 4. 4-axis & 2-axis 5A unit requires 4
Absolute encoders type	4	N	N - None, U - User selectable, E - EnDat 2.1(Digital)/2.2, S - Smart Abs, P- Panasonic, B - BiSS-A/B/C, I- SSI
Number of Absolute encoders interface	5	0	0, 1, 2
EtherCAT Master	6	1	Any (1)
Type of motors	7	0	Any (0)
I/O configuration	8	N	N - Inputs & limits: 24V/SOURCE (PNP), Outputs: 24V/SOURCE (PNP). D - Identical to (N), For compatability reasons. S - Inputs & limits: 24V/SINK (NPN). Outputs: 24V/SOURCE (PNP). R - Inputs & limits: 5V/SOURCE (PNP). Outputs: 5V/SOURCE (PNP). T - Inputs & limits: 5V/SINK (NPN). Outputs: 5V/SOURCE (PNP)

Example: UDMlc40024N010N

Field	1	2	3	4	5	6	7	8
PN UDMlc	4	002	4	N	0	1	0	N